



INTRODUCTION

About Bumblefoot

- Highest score footpad dermatitis.
- Bacterial infection- *Staphylococcus aureus*.
- Swelling, abrasion, hyperkeratosis, and ulceration of pad.
- \$460 million revenue.
- > 40% bumblefoot.

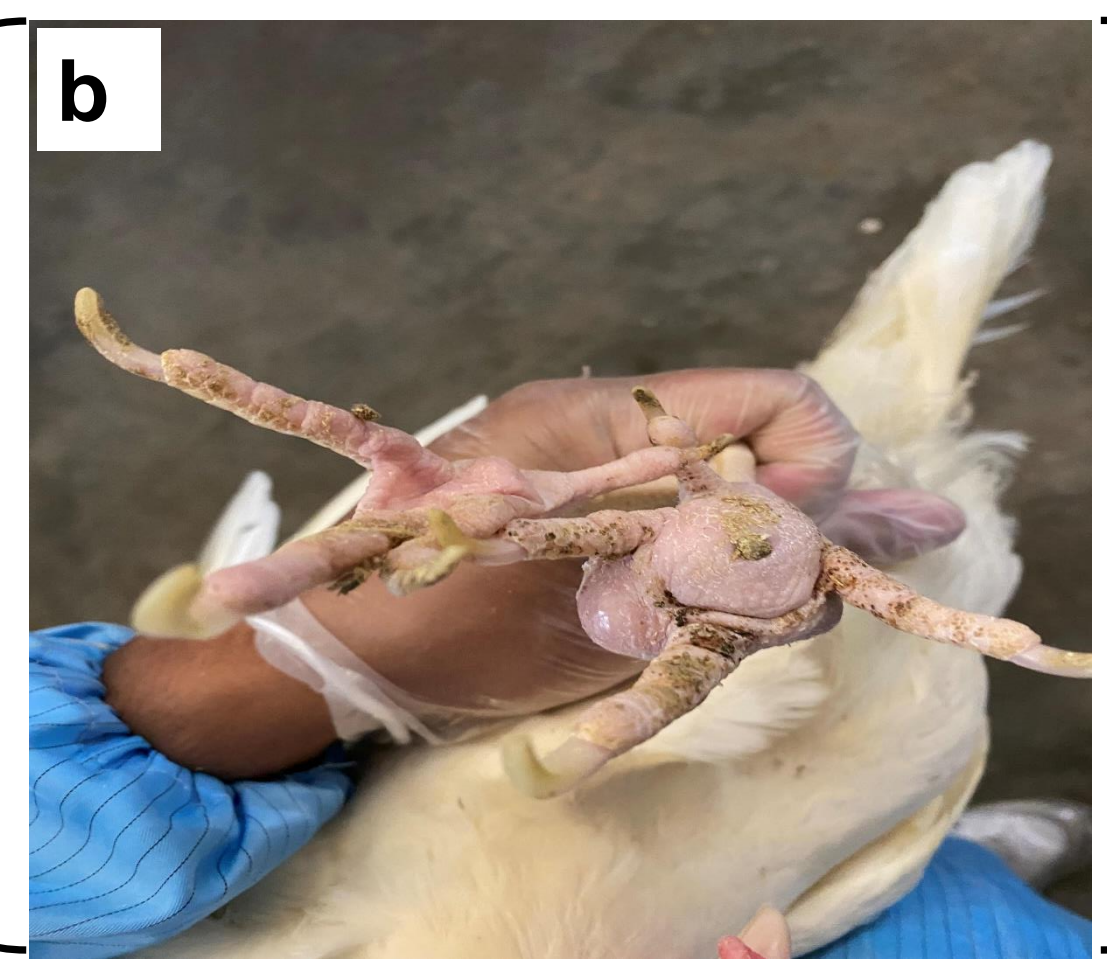


How Bumblefoot occurs?

- Litter type & quality.
- Litter moisture content.
- High stocking density.
- Manure deposition.
- Inadequate or unsanitary perches.
- Drinker design and maintenance.
- Nutritional factors.

Related research

- Visual observation.
- Invasive and holding hen.
- Infrared thermal imaging technology.



Why Bumblefoot detection(BFD) required?

- Non-invasive.
- Real-time monitoring.
- Alert the producer.

Figure 1: Bumblefoot a) side view and b) top view.

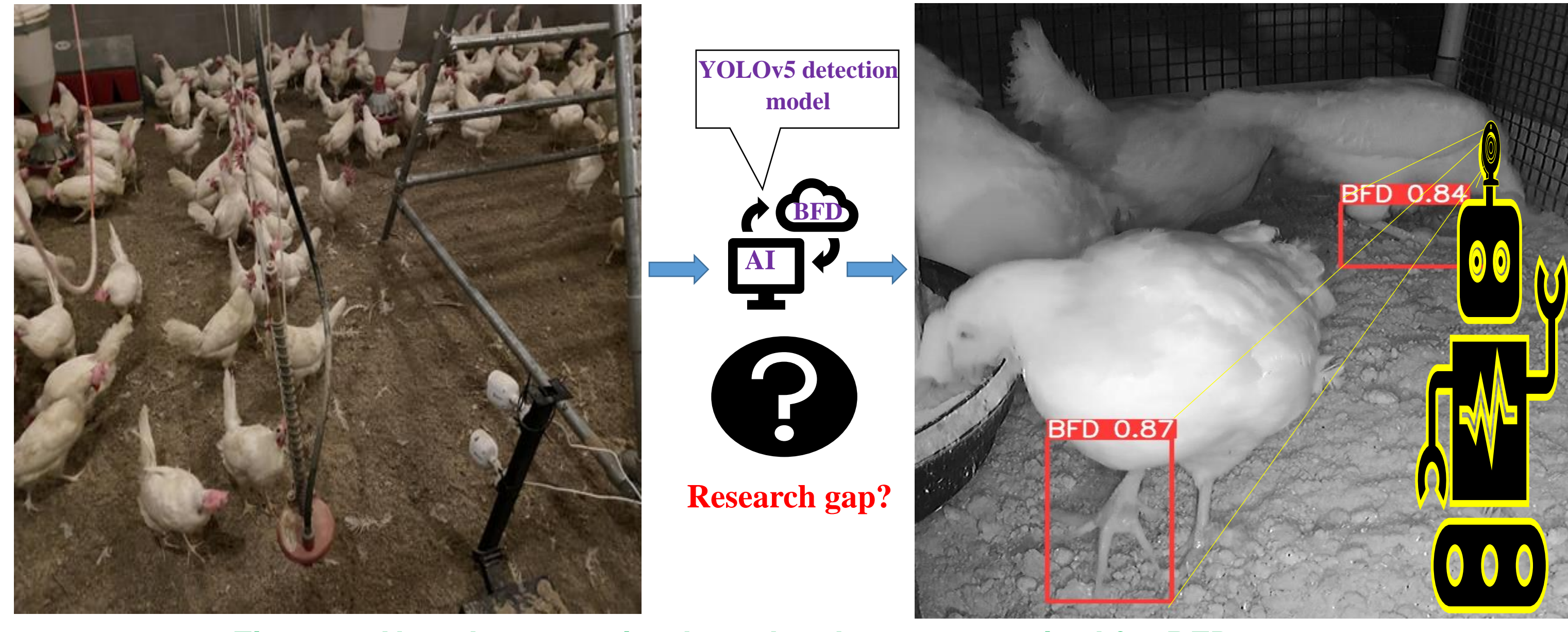


Figure 2: New deep learning-based technology required for BFD.

OBJECTIVES

- Develop and test a YOLOv5 model as a diagnostic tool for detecting clinical bumblefoot in CF layers.
- Compare the performance of YOLOv5s, YOLOv5m, and YOLOv5x-BFD model.
- Evaluate the performance of optimal YOLOv5 model under different settings.

MATERIALS AND METHODS

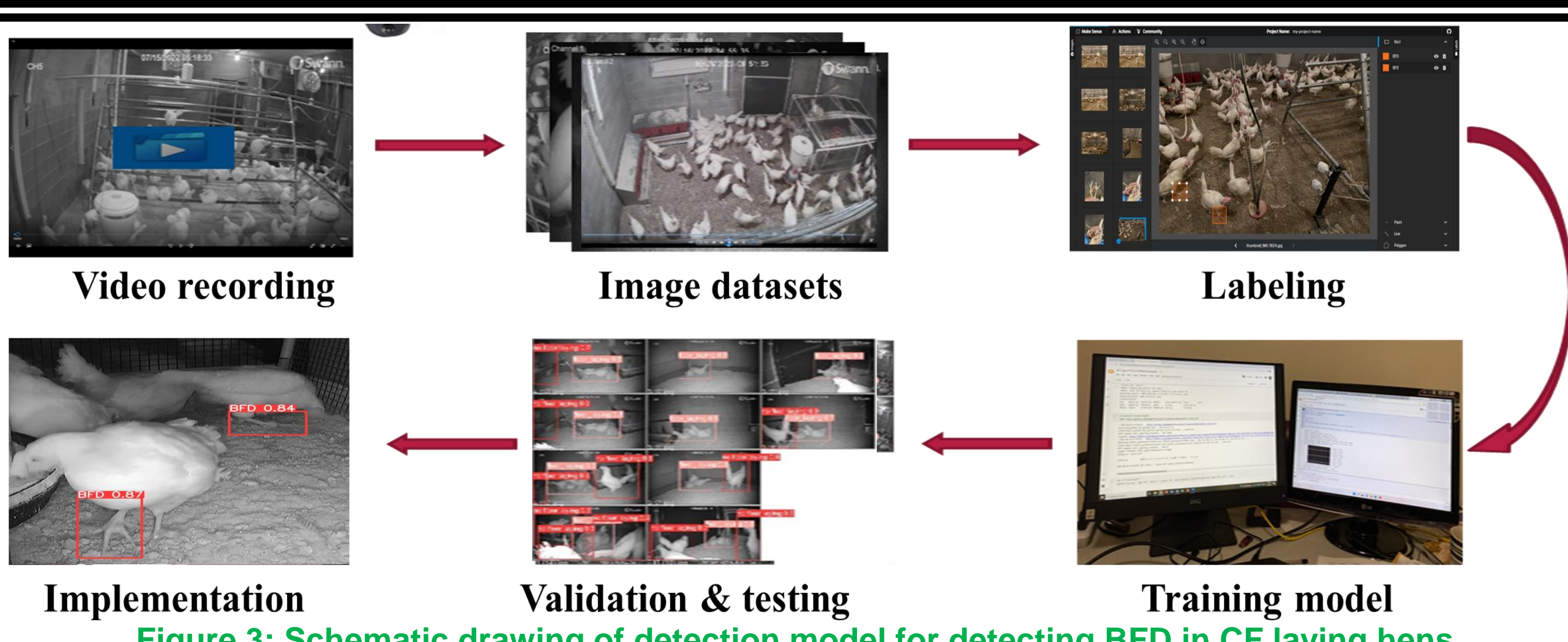


Figure 3: Schematic drawing of detection model for detecting BFD in CF laying hens.

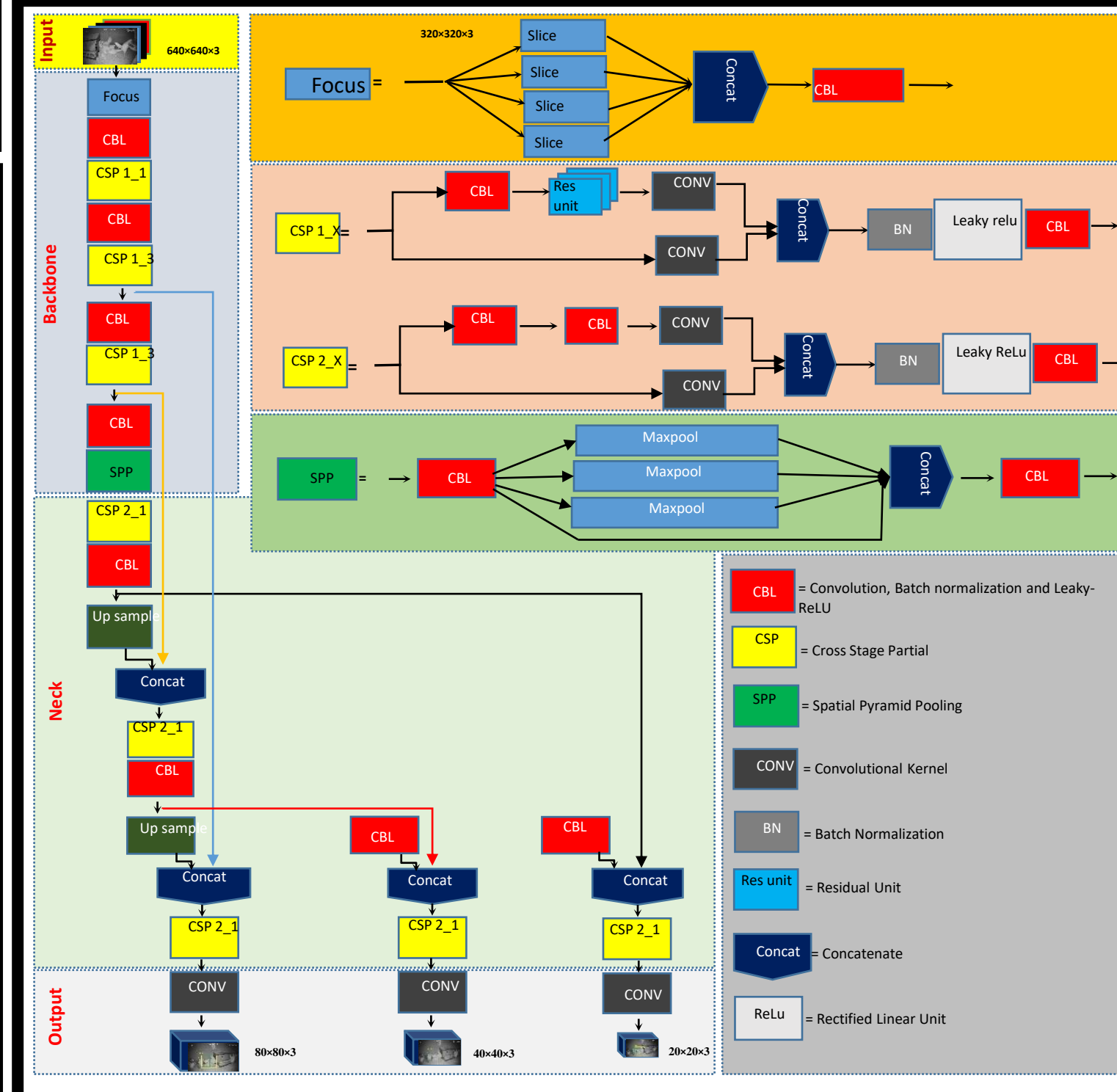


Figure 4: YOLOv5 architecture.

Model evaluation metrics:

$$Precision = \frac{TP}{TP+FP} \times 100\% \quad (1)$$

$$Recall = \frac{TP}{TP+FN} \times 100\% \quad (2)$$

$$mAP = \frac{\sum_{l=1}^L AP_l}{C} \quad (3)$$

$$F1 \text{ Score} = \frac{2 \times Recall \times Precision}{Recall + Precision} \quad (4)$$

where, TP, FP, and FN indicate true positive, false positive, and false negative values

Configuration	Parameters
CPU	64 core OCPU
Memory (RAM)	1024GB
Drive (2 counts)	7.68 TB NVMe SSD
GPU (4 counts)	4xNVIDIA® A10 (24GB)
Operating system	Ubuntu 22.10 (Kinetic Kudu)
Accelerated environment	NVIDIA CUDA
Libraries	OpenCV-python 4.1.1, Torch 1.7.0, NumPy 1.18.5, Torchvision 0.8.1

Table 1: Experimental configuration.

Data Pre-Processing:

Class	Original dataset	Train (70%)	Validation (20%)	Test (10%)
BFD _{total}	2200	1540	440	220
BFD _{batch4-32}	2200	1540	440	220
BFD _{epoch50-400}	2200	1540	440	220
BFD _{height30,50cm}	1100	770	220	110

Table 2: Data pre-processing by classes.

RESULTS AND DISCUSSIONS

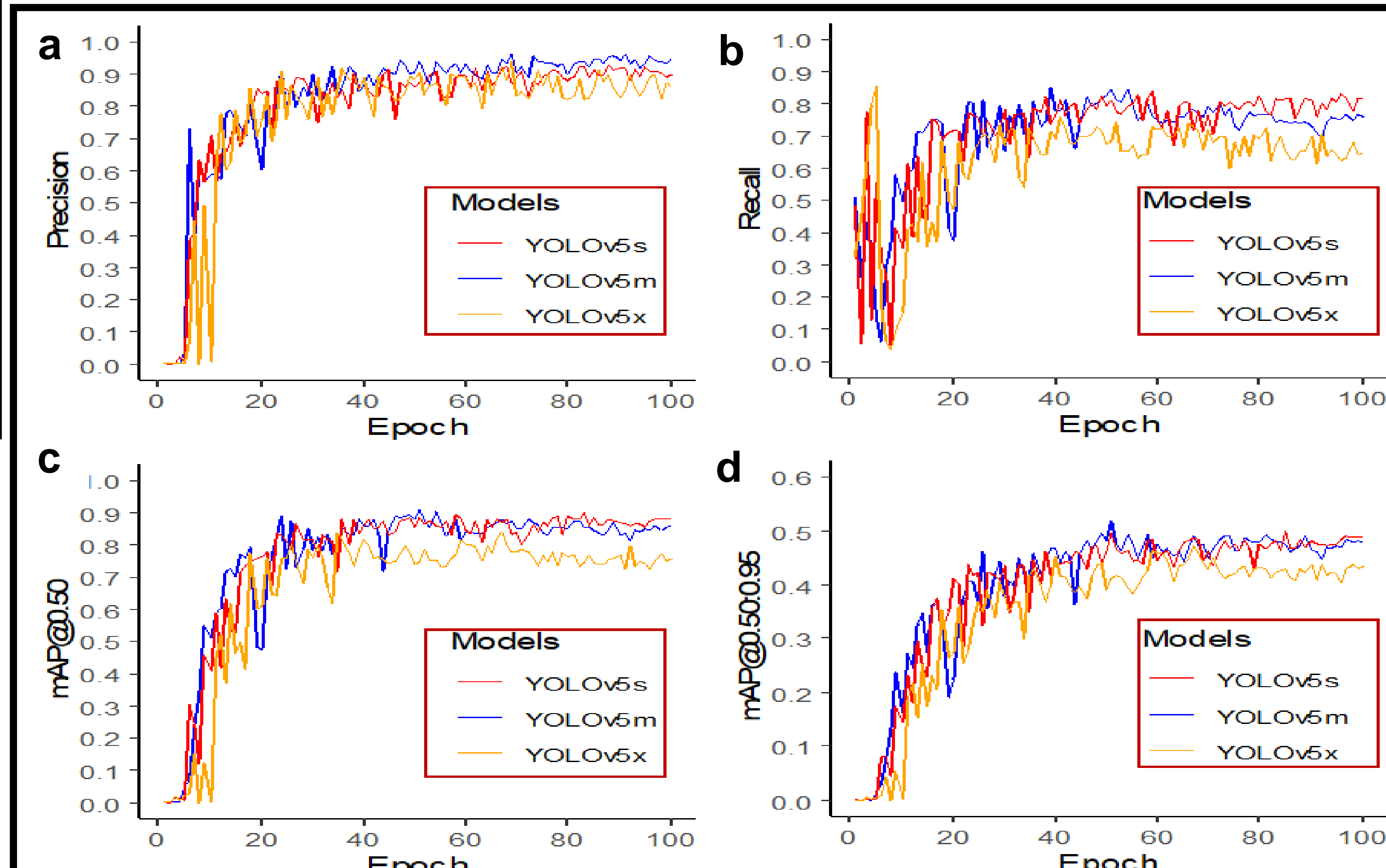


Figure 5: Model comparison curves a) Precision, b) Recall, c) mAP@0.50, and d) mAP@0.50:0.95 of different YOLOv5 models used to target BFD.

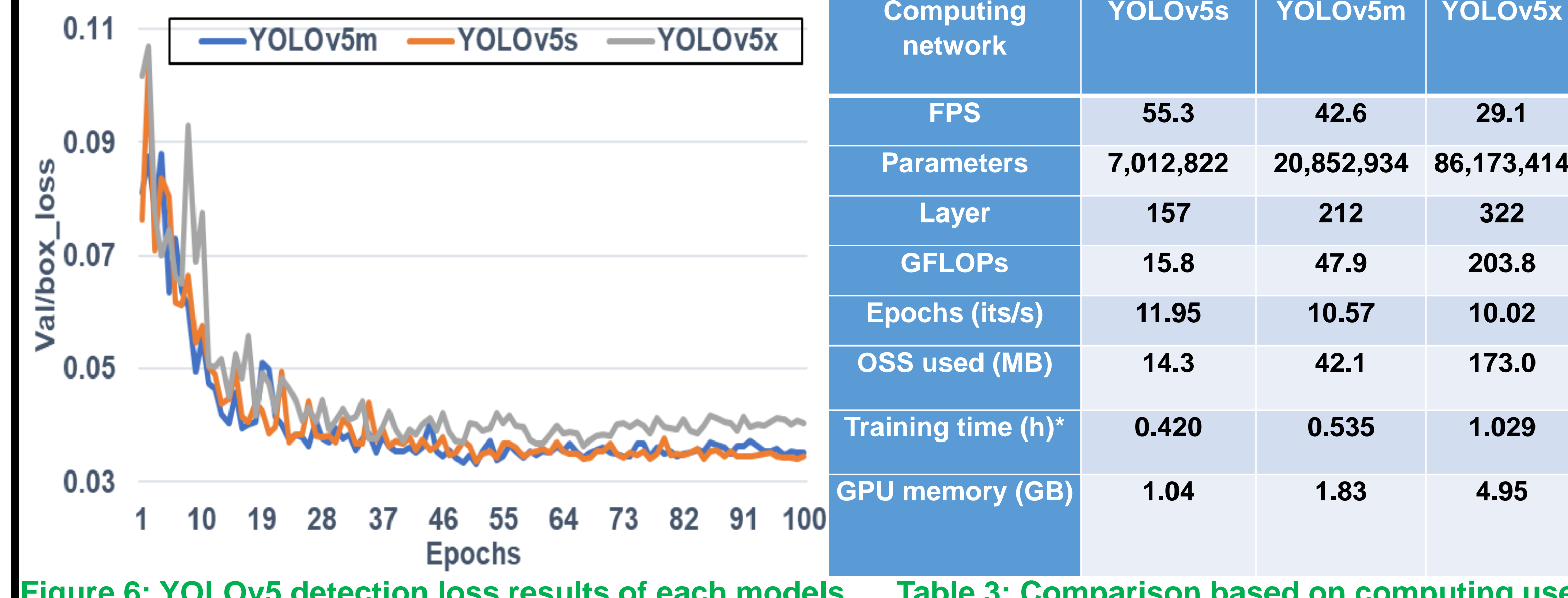


Figure 6: YOLOv5 detection loss results of each models.

Computing network	YOLOv5s	YOLOv5m	YOLOv5x
FPS	55.3	42.6	29.1
Parameters	7,012,822	20,852,934	86,173,414
Layer	157	212	322
GFLOPs	15.8	47.9	203.8
Epochs (its/s)	11.95	10.57	10.02
OSS used (MB)	14.3	42.1	173.0
Training time (h)*	0.420	0.535	1.029
GPU memory (GB)	1.04	1.83	4.95

Table 3: Comparison based on computing use.

Data summary*	Precision (%)	Recall (%)	mAP@0.50 (%)	mAP@0.50:0.95 (%)	F1-score	Training time (h)	GPU memory (GB)
BFD _{batch4}	89.2	79.8	85.5	48.9	84.0	0.932	1.27
BFD _{batch8}	89.7	86.9	90.1	52.4	88.0	0.498	1.34
BFD _{batch16}	93.7	84.6	90.9	51.8	89.0	0.535	1.83
BFD _{batch32}	94.4	75.2	85.2	48.7	84.0	0.204	3.38

Table 4: Test result of YOLOv5m model based on different batch sizes.

Data summary*	Precision (%)	Recall (%)	mAP@0.50 (%)	mAP@0.50:0.95 (%)	F1-score	Training time (h)
BFD _{epoch50}	88.0	76.0	82.2	46.6	82.0	0.258
BFD _{epoch100}	89.7	86.9	90.1	52.4	88.0	0.498
BFD _{epoch200}	94.9	77.2	90.6	51.7	85.0	0.919
BFD _{epoch400}	98.7	80.8	89.2	83.5	89.0	1.471

Table 5: Test performance of the YOLOv5m-BFD at different number of epochs.

Data summary*	Precision (%)	Recall (%)	mAP@0.50 (%)	mAP@0.50:0.95 (%)	F1-score	Training time (h)
BFD _{height30cm}	89.7	86.9	90.1	52.4	88.0	0.497
BFD _{height50cm}	77.1	64.6	70.5	39.8	71.0	0.506

Table 6: Test result of YOLOv5m BFD model based on different camera height.

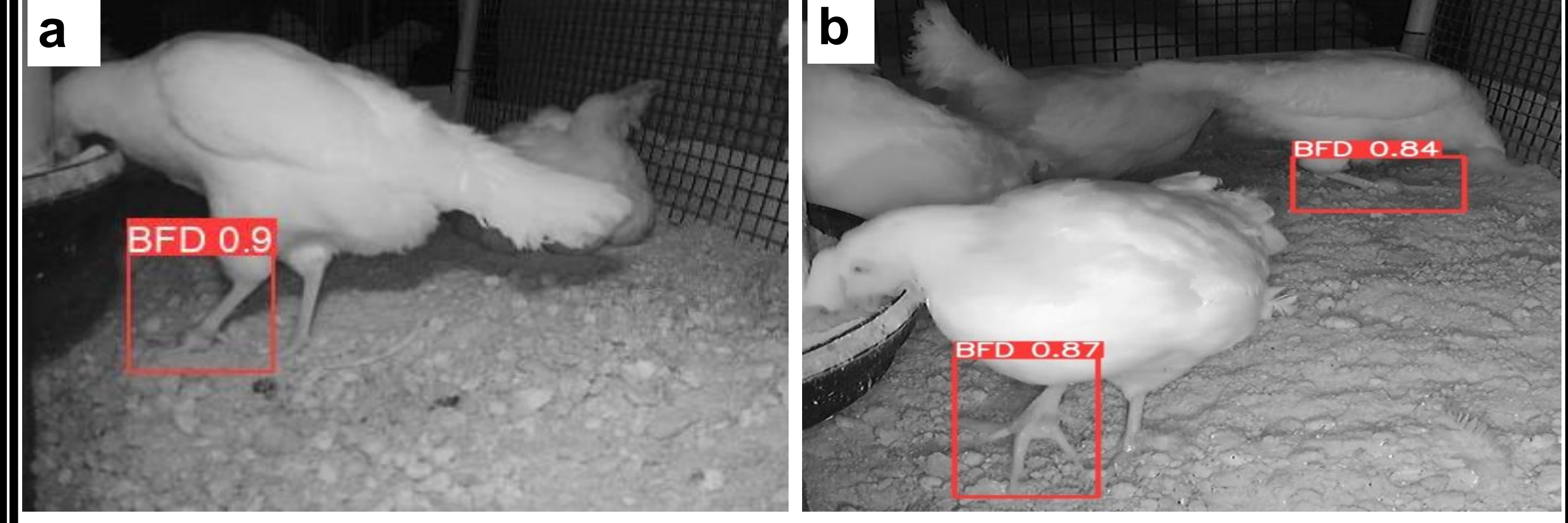


Figure 7: The BFD in test datasets using the YOLOv5m model at different camera height a) 30cm and b) 50cm.

CONCLUSIONS

- YOLOv5m-BFD model performed best with the mAP@0.50 of 90.9% compared to YOLOv5s (88.6%) and YOLOv5x (84.0%).
- Batch size 16.
- Higher number of epochs.
- Camera height of 30cm.

Future research goal:

- Commercial CF housing
- Detect non-invasive Footpad dermatitis detection model.

Acknowledgement

